

U.S. Patent Application No. 10/781,471
Reply to Office Action dated May 24, 2006

PATENT
450100-04934

IN THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application. An identifier indicating the status of each claim is provided.

Listing of Claims

1. (Currently Amended) A learning system comprising:

dialog means for obtaining the name of an object from ~~the~~ a user through a dialog with said user;

plural recognizing means for detecting a plurality of feature data of said object respectively, and for recognizing ~~the~~ above object based on ~~the~~ above detection result and the learning result of said corresponding feature data of a known object previously stored;

storing means for storing relation information, ~~in~~ that said name of said known object is connected with the recognition result of ~~the~~ above known object by each of said recognizing means; and

control means, for determining that if determining that said object is a new object based on the name of said object obtained by said dialog means, the recognition result of the ~~above~~ object by each of said recognizing means, and said relation information stored in said storing means, for making said needed recognizing means perform the learning of said corresponding feature data of ~~the~~ above object, and making said storing means ~~newly store this~~ obtained the relation information ~~on~~ the ~~above~~ object,

wherein said control means manages the learning achievement degrees of said known object by said respective recognizing means, and

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whercin if said control means determines that said object is a known
object based on the name of said object obtained by said dialog means, the control means makes
said predetermined recognizing means perform the learning of said corresponding feature of the
object, and updates said corresponding relation information according to the obtained new
learning achievement degree.

2. (Cancelled)

3. (Currently Amended) The learning system according to claim 1,
wherein: [[;]]

each of said recognizing means starts collecting learning data for performing the learning of said corresponding feature of the ~~above~~ object before said dialog means obtains said name of said object, and performs the learning of said corresponding feature of said object with the ~~above~~ collected learning data.

4. (Currently Amended) The learning system according to claim 3,
wherein: [[;]]

even if each of said recognizing means ~~could~~ does not collect a predetermined amount of said learning data, ~~it~~ the recognizing means performs the learning of said corresponding feature of said object with the ~~above~~ collected learning data.

5. (Currently Amended) The learning system according to claim 1,
wherein: [[;]]

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if the learning of said corresponding feature of said object is stopped in the middle of the learning, each of said recognizing means stores the ~~above~~ a halfway learning result until that time, and starts the next learning of said corresponding feature of the ~~above~~ object from the ~~above~~ halfway point.

6. (Currently Amended) The learning system according to claim 1, wherein:
~~said object is said user being the other party of the dialog; and~~
if the learning of said user by one or all more of said recognizing means is insufficient, said dialog means executes the processing to prolong the dialog with said user.

7. (Currently Amended) The learning system according to claim 6,
wherein:~~[[;]]~~

~~to prolong the dialog with said user, said dialog means executes the processing to make a dialog so that said recognizing means is insufficient in the learning of said object easily perform that learning.~~

8. (Currently Amended) The learning system according to claim 2, wherein:~~[[;]]~~

~~said control means makes said predetermined recognizing means that is determined based on said learning achievement degree of said object by each of said recognizing means start the learning of said corresponding feature of the ~~above~~ object, from the state according to the present learning achievement degree of the ~~above~~ object by the ~~above~~~~

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recognizing means.

9. (Currently Amended) The learning system according to claim 8, wherein:
~~said control means makes said storing means stores data for the present learning achievement degree by each of said recognizing means, and manages the learning achievement degrees.~~[[;]]-and
~~said control means or said storing means performs time attenuation to said learning achievement degrees.~~

10. (Currently Amended) A learning method comprising:
~~the first step for obtaining the a name of an object from the a user through a dialog with said user;~~[[,]]-and for
recognizing the above object based on the a detection result of a plurality of feature data of said object and the a learning results of said respective features of said known object previously stored; and
~~the second step, if it is determined that determining whether said object is a new object based on the obtained name of said object, the recognition results based on said respective feature data of the above object, and relation information in that said name of said known object that is connected with the recognition results of said respective feature data of the above known object;~~[[,]]-for
performing the learning of said needed feature data; of the above object[[,]]-and
newly
~~storing thus the obtained relation information on the above object;~~

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managing the learning achievement degrees of said respective features;
determining whether said object is a known object based on the obtained name of
said object, if so, the recognition results of said respective features of the object, and said stored
relation information, the learning of said predetermined feature determined based on said
learning achievement degrees of said respective features of the object is performed; and
updating the corresponding relation information according to the obtained new
learning achievement degree.

11. (Cancelled)

12. (Currently Amended) The learning method according to claim 10,
wherein:

~~in said first step, collecting learning data for performing the learning of said~~
~~respective features of the above object is started before said name of said object is obtained; and~~
~~in said second step, the learning of said respective features of said object is~~
~~performed with the above collected learning data.~~

13. (Currently Amended) The learning method according to claim 12,
wherein:~~[[;]]~~

~~in said second step, even if a predetermined amount of said learning data could be~~
~~not be collected, the learning of said corresponding feature of said object is performed with the~~
~~above collected learning data.~~

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14. (Currently Amended) The learning method according to claim 10,
wherein:

~~in said second step, if the learning of said corresponding feature of said object is stopped in the middle of during the learning, the above halfway learning result until that time is stored; and~~

~~the next additional learning of said corresponding feature of the above object is started from the above halfway point.~~

15. (Currently Amended) The learning method according to claim 10,
wherein:

~~said object is said user being the other party of the dialog; and~~

~~in said second step, if the learning of one or all more of said features of said user is insufficient, the processing to prolong the dialog with said user is performed.~~

16. (Currently Amended) The learning method according to claim 15,
wherein:[[;]]

to prolong the dialog with said user, the processing to make a dialog so that the learning of said feature, insufficient in the learning, of said object ~~can be easily~~ is performed.

17. (Currently Amended) The learning method according to ~~claim 11~~ claim 10, wherein:

~~in said second step, the learning of said predetermined feature of said object determined based on said learning achievement degrees of said respective features of said object~~

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is started from the state according to the present learning achievement degree of the ~~above~~
feature.

18. (Currently Amended) The learning method according to ~~claim 11~~ claim
10, wherein: ~~[[;]]~~

time attenuation is performed to said learning achievement degrees.

19. (Currently Amended) A robot apparatus comprising:
dialog means for obtaining ~~the~~ a name of an object from ~~the~~ a user through a
dialog with said user;

plural recognizing means for detecting ~~the~~ one or more predetermined different
features of said object ~~respectively~~, and for recognizing the ~~above~~ object based on the ~~above~~
detection result and the learning result of said corresponding feature of said known object
previously stored;

storing means for storing relation information in ~~that~~ said name of such that said
known object is connected with the recognition result of the ~~above~~ known object by each of said
recognizing means; and

control means, ~~if~~ for determining that said object is a new object based on the
name of said object obtained by said dialog means, the recognition result of the ~~above~~ object by
each of said recognizing means, and said relation information stored in said storing means, ~~for~~
~~making~~ ~~said~~ ~~needed~~ ~~recognizing~~ means perform the learning ~~of~~ ~~said~~ corresponding feature of the
~~above~~ object, and ~~making~~ ~~said~~ ~~storing~~ means ~~newly~~ store ~~thus~~ obtained storing relation
information on the ~~above~~ object;

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wherein said control means manages the learning achievement degrees of said known object by said recognizing means, and

wherein if said control means determines that said object is a known object based on the name of said object obtained by said dialog means, the recognition results of the object by said recognizing means, and said relation information stored in said storing means, the recognizing means perform the learning of said corresponding feature of the object, and updates said corresponding relation information according to obtained new learning achievement degree.

20. (Cancelled)

21. (Currently Amended) The robot apparatus according to claim 19,
wherein:[];[]

each of said recognizing means starts collecting collects learning data for performing the learning of said corresponding feature of the above object before said dialog means obtains said name of said object, and performs the learning of said corresponding feature of said object with the above collected learning data.

22. (Currently Amended) The robot apparatus according to claim 21,
wherein:[];[]

even if each of when said recognizing means could does not collect a predetermined amount of said learning data, if the recognizing means performs the learning of

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said corresponding feature of said object with the ~~above~~ collected learning data.

23. (Currently Amended) The robot apparatus according to claim 19,
wherein: [[;]]

~~if when the learning of said corresponding feature of said object is stopped during in the middle of the learning, each of said recognizing means stores the ~~above~~ a halfway learning result until that time, and starts the next learning of said corresponding feature of the ~~above~~ object from the ~~above~~ halfway point.~~

24. (Currently Amended) The robot apparatus according to claim 19,
wherein:

~~said object is said user being the other party of the dialog, and if the learning of said user by one or all of said recognizing means is insufficient, said dialog means executes the processing to prolong the dialog with said user.~~

25. (Currently Amended) The robot apparatus according to claim 24,
wherein: [[;]]

~~to prolong the dialog with said user, said dialog means executes the processing to make a dialog so that said recognizing means insufficient in the learning of said object easily perform that learning.~~

26. (Currently Amended) The robot apparatus according to claim 20, claim 19, wherein: [[;]]

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~~said control means makes said predetermined recognizing means that is~~
~~determined based on said learning achievement degree of said object by each of said recognizing~~
means start the learning of said corresponding feature of the ~~above~~ object, from the state
according to ~~the~~ a present learning achievement degree of the ~~above~~ object by the ~~above~~
recognizing means.

27. (Currently Amended) The robot apparatus according to claim 26,
wherein:

~~said control means makes said storing means stores~~ data for the present learning
achievement degree by each of said recognizing means, and manages the learning achievement
degrees; and

said control means or said storing means performs time attenuation to said
learning achievement degrees.